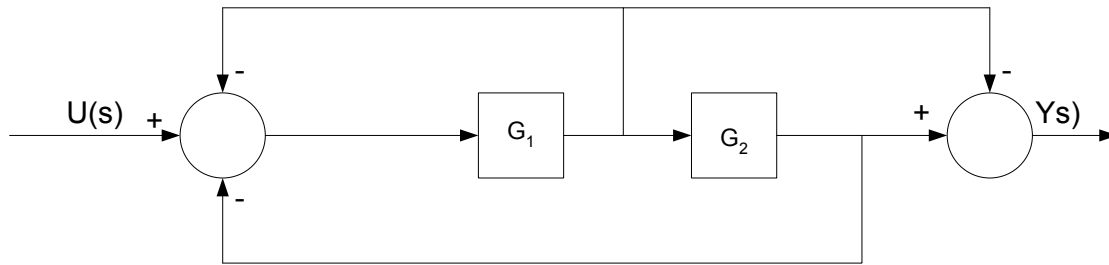


ECE 386  
 HOMEWORK-1  
 DUE DATE: 29-APRIL-2015

Q1) Obtain the transfer function  $T(s) = \frac{Y(s)}{U(s)}$  for the system whose state-flow diagram is given below. **(20 POINTS)**



Q2) The input- disturbance-output relation of a system in Laplace Domain is given by the formula

$$Y(s) = G_1(s)G_2(s)U(s) + G_2(s)D(s)$$

where  $G_1(s) = \frac{7}{s+7}$  and  $G_2(s) = \frac{1}{s+1}$ . Assume  $D(s) = 0$  (no disturbance) and  $U(s) = \sigma(s) = \frac{1}{s}$  (input is unit step input). Find  $y(t)$  (output signal in time domain). **(20 POINTS)**

Q3) A polynomial  $x(s)$  is given by the formula

$$x(s) = s^4 - 4s^3 - 7s^2 + 22s + 24$$

Using Routh-Hurwitz method find the number of roots of  $x(s)$  on the Open Right Half Plane (ORHP). **(20 POINTS)**

Q4) A system is given by the matrix differential equation

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u$$

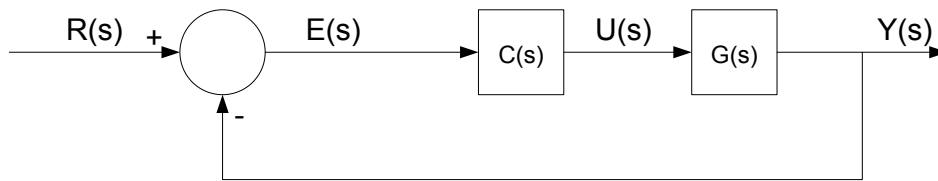
$$y = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

a) Find the transfer function  $T(s) = \frac{Y(s)}{U(s)}$ . **(10 POINTS)**

b) Obtain the state flow diagram for this system in Laplace domain. **(10 POINTS)**

**Hint:** In the state flow diagram  $U(s)$  will be the input  $Y(s)$  will be the output and  $X_1(s)$  and  $X_2(s)$  will be the states. In the state flow diagram only use integrators whose transfer function is  $\frac{1}{s}$  (in rectangles) and summation points (in circles) while drawing the mathematical relation between the signals ( $U(s)$ ,  $Y(s)$ ,  $X_1(s)$  and  $X_2(s)$ ).

Q5) A **negative unity feedback** system is given as below where  $R(s)$  is the reference signal,  $E(s)$  is the error signal,  $U(s)$  is the input signal,  $Y(s)$  is the output signal,  $C(s)$  is the controller transfer function and  $G(s)$  is the plant transfer function. **(20 POINTS)**



a) Write the error signal  $E(s)$  in terms of  $R(s)$ ,  $C(s)$  and  $G(s)$ . **(3 POINTS)**

b) Assume  $C(s)G(s) = \frac{5}{s(s+1)(s+5)}$ . Find the steady state error value ' $e_{ss}$ ' if the reference signal  $R(s)$  is a unit step signal ( $R(s) = \sigma(s) = \frac{1}{s}$ ). **(3 POINTS)**

c) Assume  $C(s)G(s) = \frac{5}{(s+1)(s+5)}$ . Find the steady state error value ' $e_{ss}$ ' if the reference signal  $R(s)$  is a unit step signal ( $R(s) = \sigma(s) = \frac{1}{s}$ ). **(3 POINTS)**

d) Assume  $C(s)G(s) = \frac{5}{(s+1)(s+5)}$ . Find the steady state error value ' $e_{ss}$ ' if the reference signal  $R(s)$  is a unit ramp signal ( $R(s) = \sigma(s) = \frac{1}{s^2}$ ). **(3 POINTS)**

e) Assume  $C(s)G(s) = \frac{1}{(s)(s+5)}$ . Find the transfer function of the closed loop system  $T(s) = \frac{Y(s)}{R(s)}$ . Also find the damping ratio, resonant angular frequency, rise time, settling time and maximum overshoot (%). **(8 POINTS)**